

Motivation

Why do we study median graphs?

- They first appeared in the study of distributive lattices
 $X_{\text{set}} \quad (\mathcal{P}(X), \cap, \cup) \leftarrow \text{distributive lattice}$
 $\uparrow \quad \uparrow$
 $\text{gcd} \quad \text{lcm}$
 $\rightarrow A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$
&
 $\rightarrow A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$
- phylogenetics (study of relations between living/living or living/extinct species)
- social choice theory & voting systems.

→ Median graphs are the 1-skeleton of $\text{CAT}(0)$ cube complexes.

→ $\text{CAT}(0)$ median graphs ~~cannot~~ ^{are easier} to deal with than $\text{CAT}(0)$ cube complexes

Sageev: $\text{CAT}(0)$ geometry is given by the behaviour of intersection of hyperplanes in these complexes.

→ isometries of median graphs are more understood than those of $\text{CAT}(0)$ cube complexes, for the reason that:

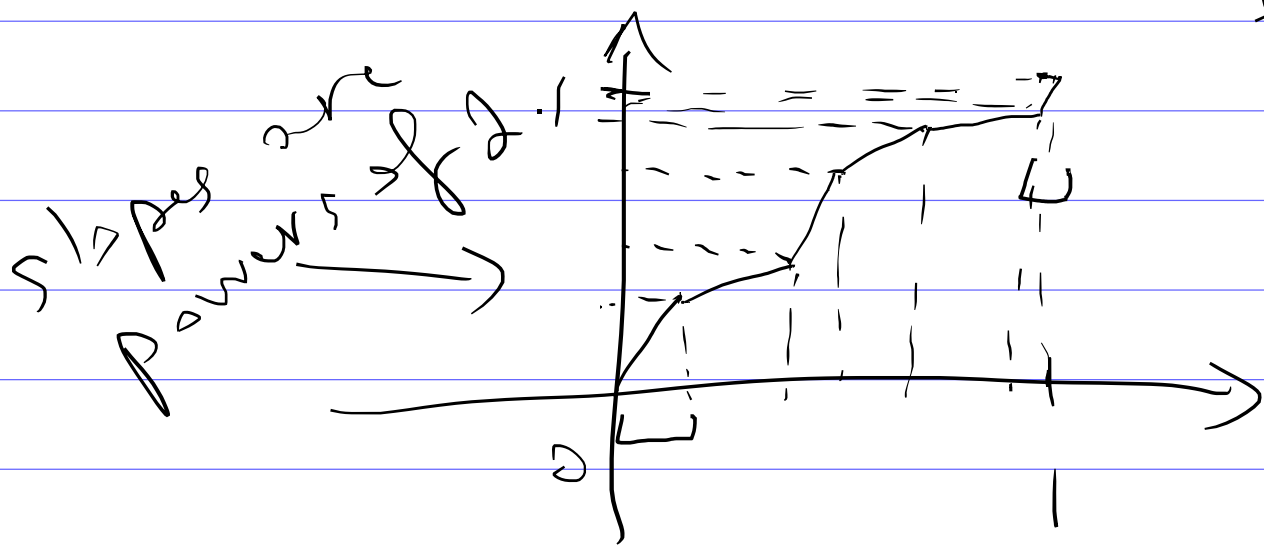
	Median graphs	$\text{CCCAT}(0)$
Isometries	→ periodic (elliptic)	→ periodic
	→ loxodromic (hyperbolic)	→ loxodromic
		→ parabolic

Bridson

g periodic: $g \cdot x = x \quad (\exists x \in X)$

g loxodromic: $\exists$ axis in the complex (or graph) on which it acts as a translation

g parabolic: the rest (classification of the isometries of the Thompson group)
 $F \curvearrowright \text{CCCAT}(0)$



$$f: [0,1] \rightarrow [0,1]$$

$$f(0) = 0$$

$$f(1) = 1$$

piecewise affine
increasing

At most countably infinitely
many breaking points, which happen
at dyadic numbers between 0 and 1.

$$\frac{m}{2^n} \in \mathbb{N}.$$

$g \in F$ is an isometry

g is parabolic iff $g'(0^+) \times g'(1^-) \neq 1$.

$F \cap$ median graph $\leftarrow$ X parabolic isometry

Refer to Dan Titus Salajan: CAT(0) geometry
for the Thompson group.

Algebraic consequences on the group acting on a median graph

$\rightarrow$ free $(\Rightarrow) G \cap$ tree $\leftarrow$ median graph

$\rightarrow G \cap$ X median graph

$\Downarrow$

$G \not\cong BS(n, m) = \langle a, t \mid ta^n t^{-1} = a^m \rangle$
if $m \neq -n$

proper action.

glaxodromic

$$g^p = t g^q t^{-1}$$

$$p = \pm q$$

→ a-t-nearability : (Haagerup property)

$G^{Proper} \rightarrow X$ median graph

$\Downarrow$

G has the Haagerup property

$\Leftrightarrow G \curvearrowright \mathcal{H}$ Hilbert space

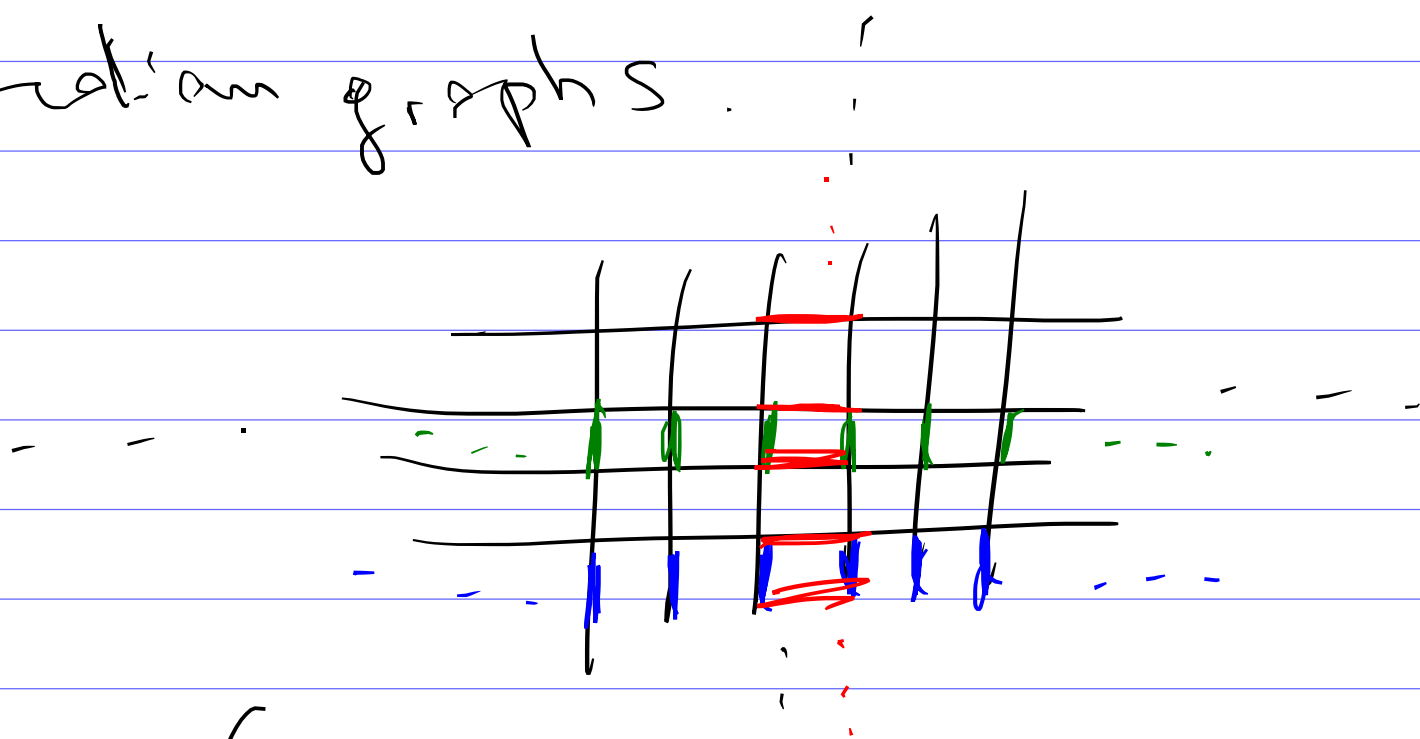
by proper continuous affine isometries.

eg: the case of the Thompson group F

We can construct a median graph on which

F acts properly $\Rightarrow F$ is a-t-nearable.

Last time we talked about hyperplanes
in median graphs.



Theorem: (The geometry of median graphs reduces
to the combinatorics of its hyperplanes)

X median graph, then:

- (1) Every hyperplane divides its exactly two halfspaces.
- (2) Carriers, fibres and halfspaces are all convex subgraphs of X .
- (3) Every geodesic in X crosses each hyperplane at most once.
- (4) The distance between two points in X is equal to the number of hyperplanes separating them.

Positions of two hyperplanes:

X - set, $J_1, J_2 \in \mathcal{H}(X)$

(1) Transversality

J_1 and J_2 are transverse ($J_1 \perp J_2$)

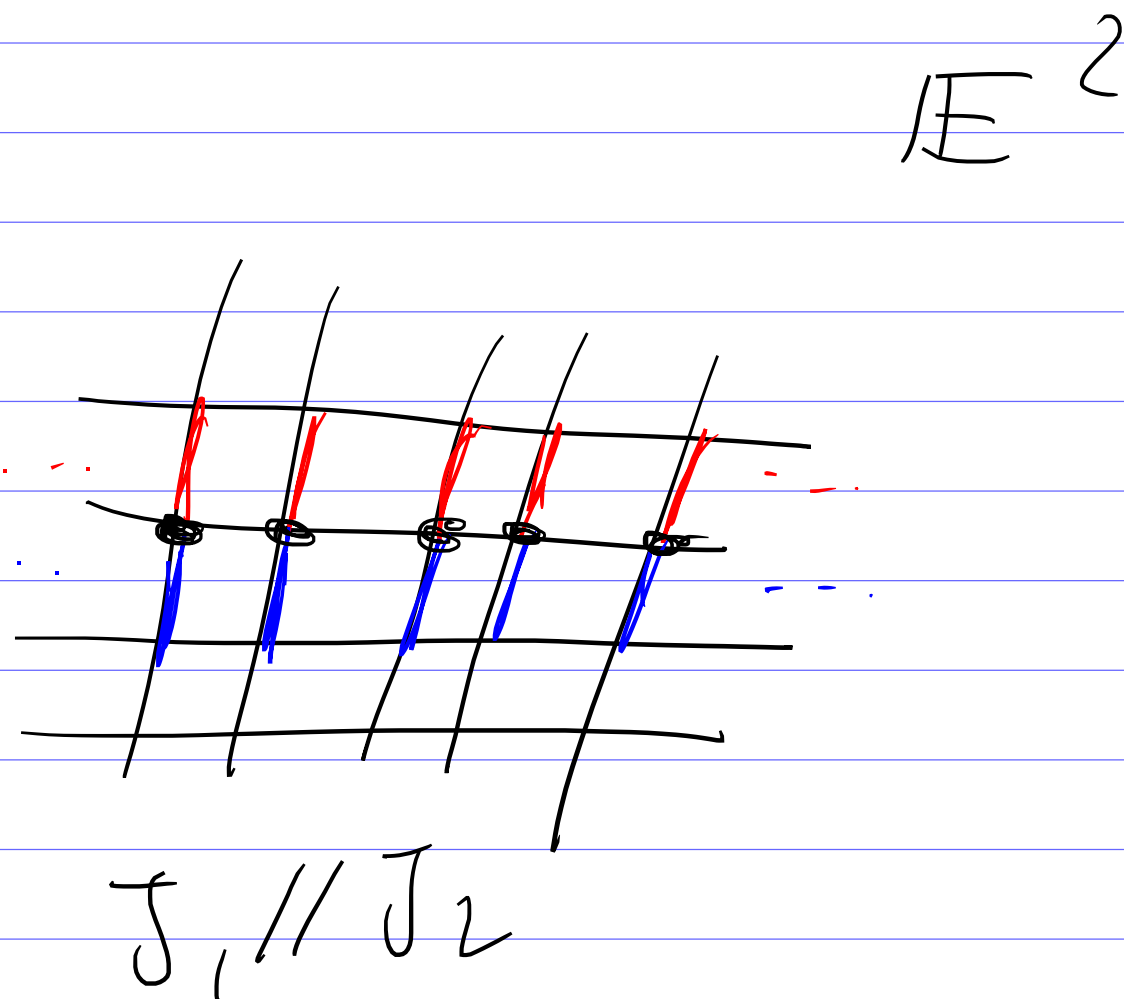
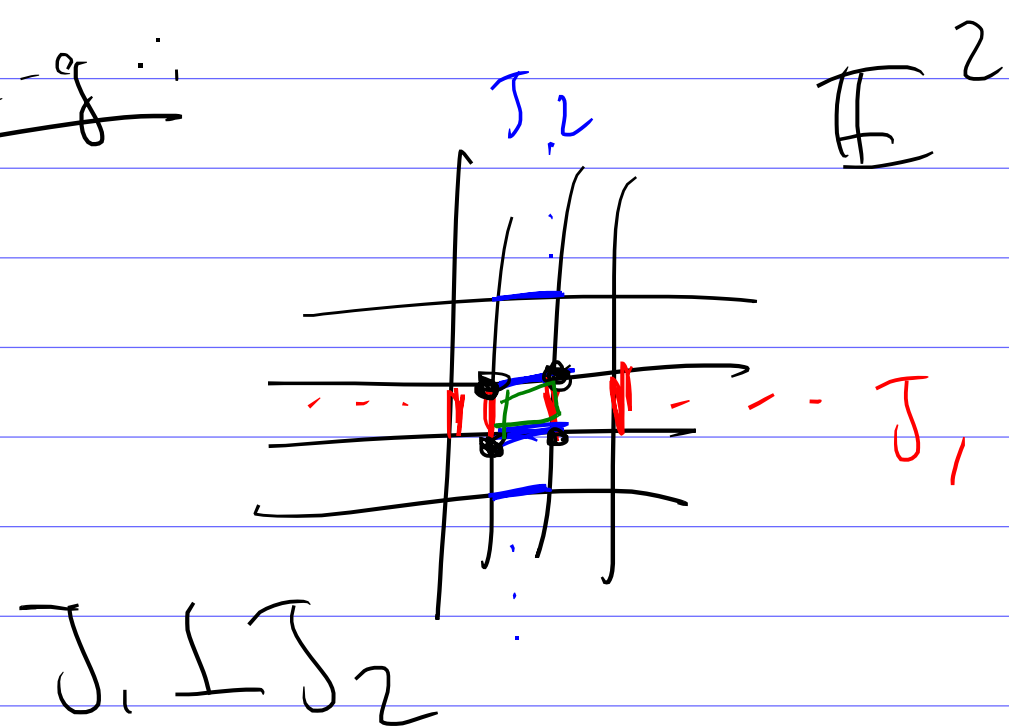
iff J_1 and J_2 intersect and span a 4-cycle.

(2) Parallelism:

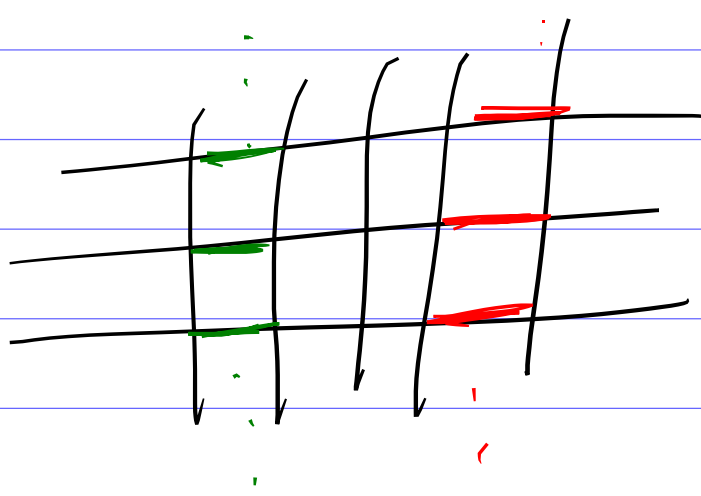
J_1 and J_2 are parallel iff ($J_1 \parallel J_2$)

iff J_1 and J_2 intersect but do not span a 4-cycle.

e.g.:



Neither parallel nor transverse



Interesting properties about hyperplanes:

(1) A hyperplane cannot be transverse to itself.

(2) J_1 and J_2 transverse iff

$$\begin{cases} J_1^+ \cap J_2^+ \neq \emptyset \\ J_1^- \cap J_2^- \neq \emptyset \\ J_1^+ \cap J_2^- \neq \emptyset \\ J_1^- \cap J_2^+ \neq \emptyset \end{cases}$$

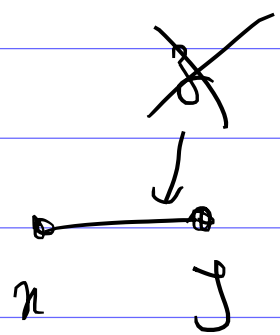
(3) A subgraph D of X is a halfspace for some hyperplane $J \in \mathcal{H}(X)$ iff D and D^c are both convex.

Projections on convex subgraphs

Theorem.

Let X be a median graph.

Let $x \in X$ and $Y \subseteq X$ convex.
Subgraph

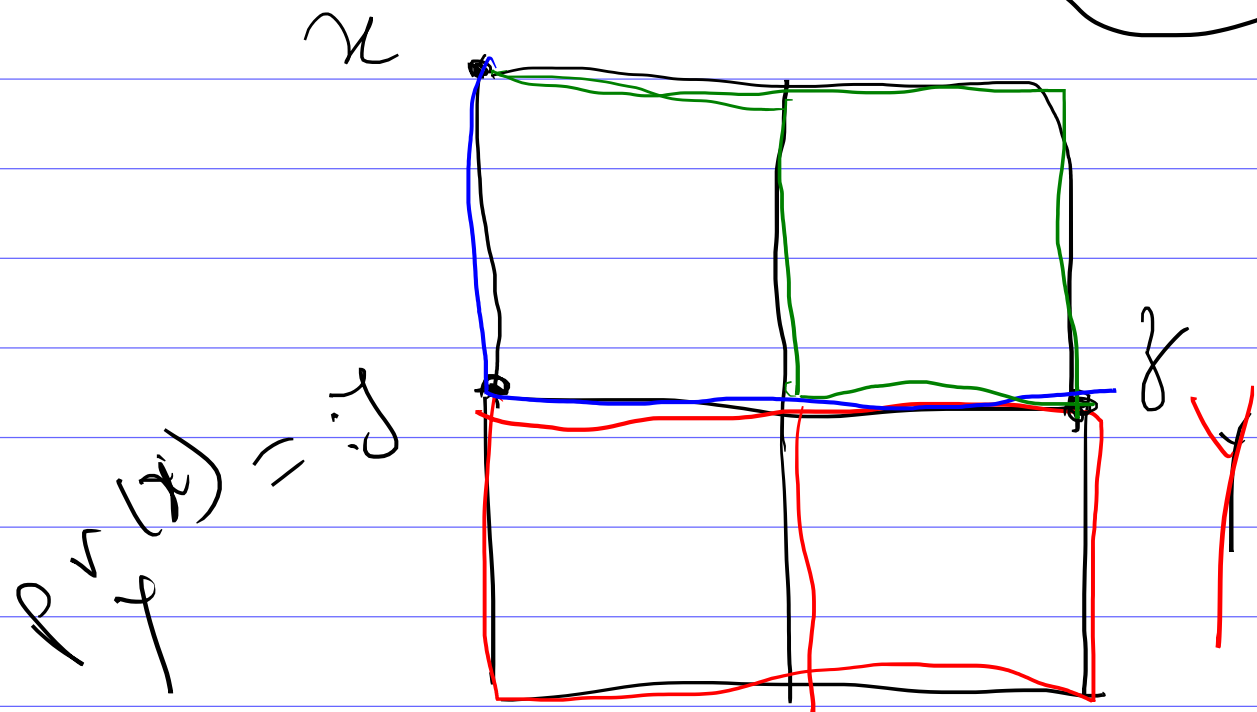
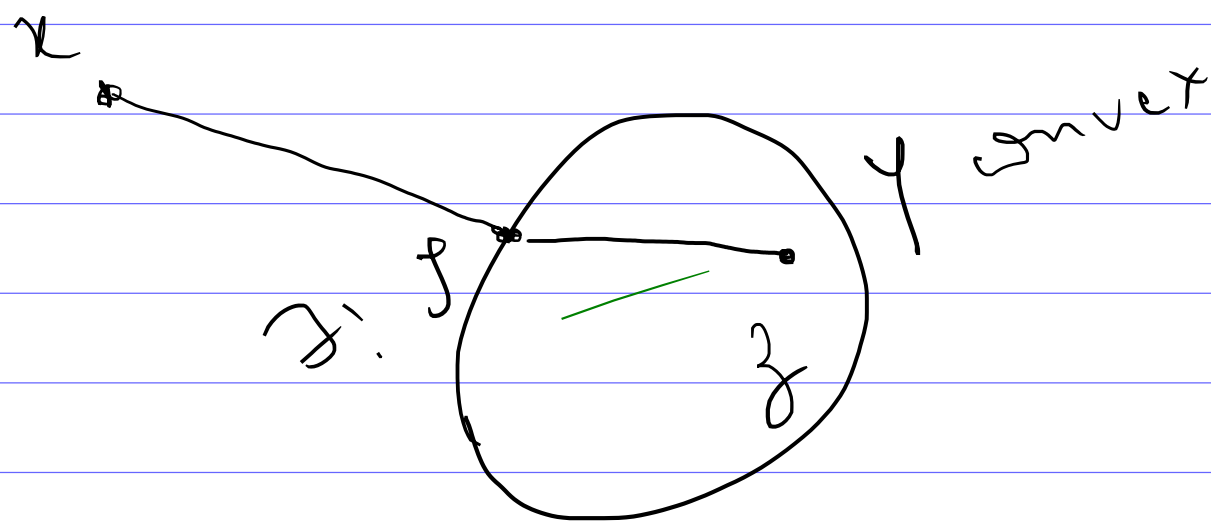


Then there exists a unique vertex $y \in Y$ minimizing the distance from x to Y .

Moreover, for every $z \in Y$, there exists a geodesic from x to z passing through y .

X metric

$$[x, y] \cup [y, z] = \text{geodesic.}$$



Pf. of the theorem above

$x \in X$

Y convex.

Let $y_1, y_2 \in Y$ minimizing the distance to x .

$$\text{Let } m := \mu(x, y_1, y_2).$$

$$m \in [y_1, y_2] \xRightarrow{+Y \text{ is convex}} [y_1, y_2] \subseteq Y \\ \Rightarrow m \in Y.$$

$$m \in [x, y_1] \Rightarrow d(x, y_1) = d(x, m) + d(m, y_1) (*)$$

$$\Rightarrow d(x, m) \leq d(x, y_1) \quad \left. \vphantom{\Rightarrow} \right\} + \quad \uparrow$$

$$\text{But } \Rightarrow d(x, y_1) \leq d(x, m) \\ \Rightarrow d(m, y_1) = 0 \Rightarrow m \equiv y_1$$

Again $\Rightarrow m \equiv j_2$

$\Rightarrow j_1 \equiv j_2 \Rightarrow \exists! j \in \Gamma$ minimizing $d(x, j)$.

Let $j \in \Gamma$.

$m := \mu(x, j, z)$.

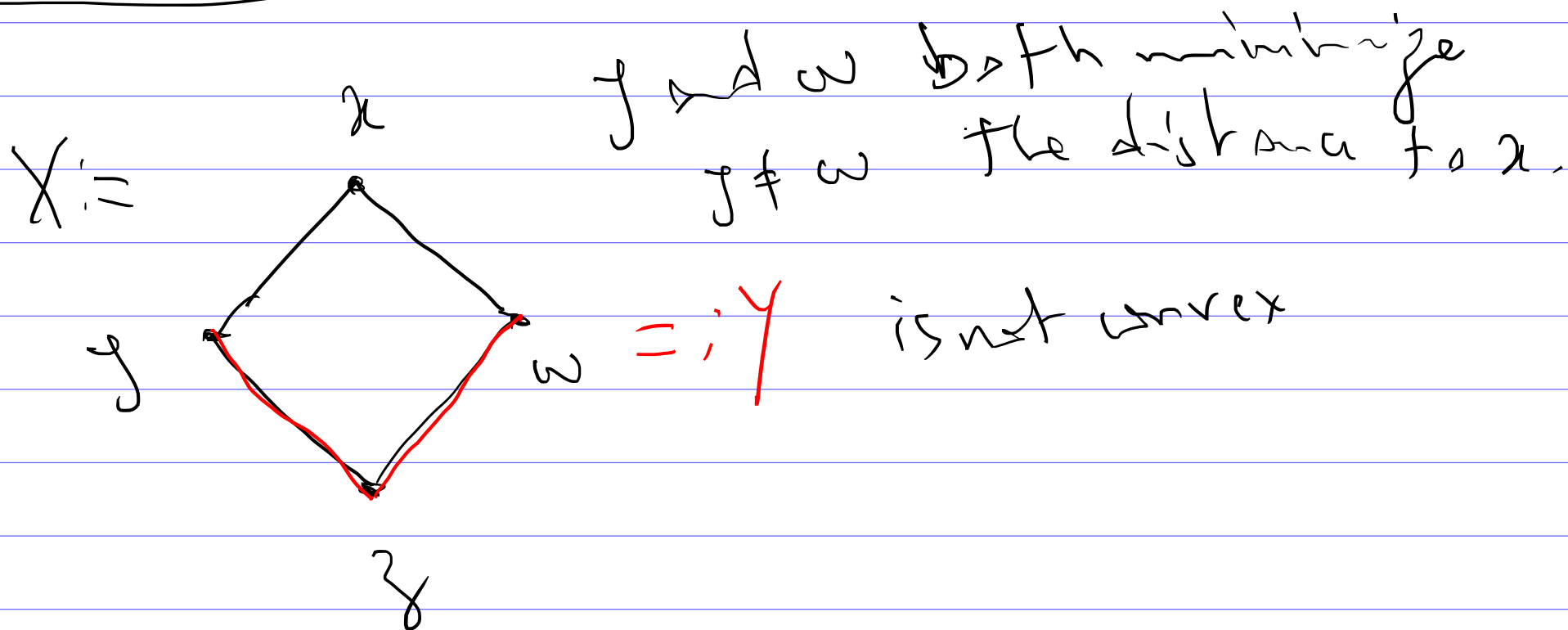
$m \in [j, z] \subseteq \Gamma$ + Γ convex $\Rightarrow m \in \Gamma$.

$d(x, j) = d(x, m) + d(m, j)$
 $\Rightarrow m \equiv j$.

$m = \mu(x, j, z) \Rightarrow m \in [x, z] \Rightarrow j \in [x, z]$.

□

none j : "projecting" onto non-convex subgraphs



Property:

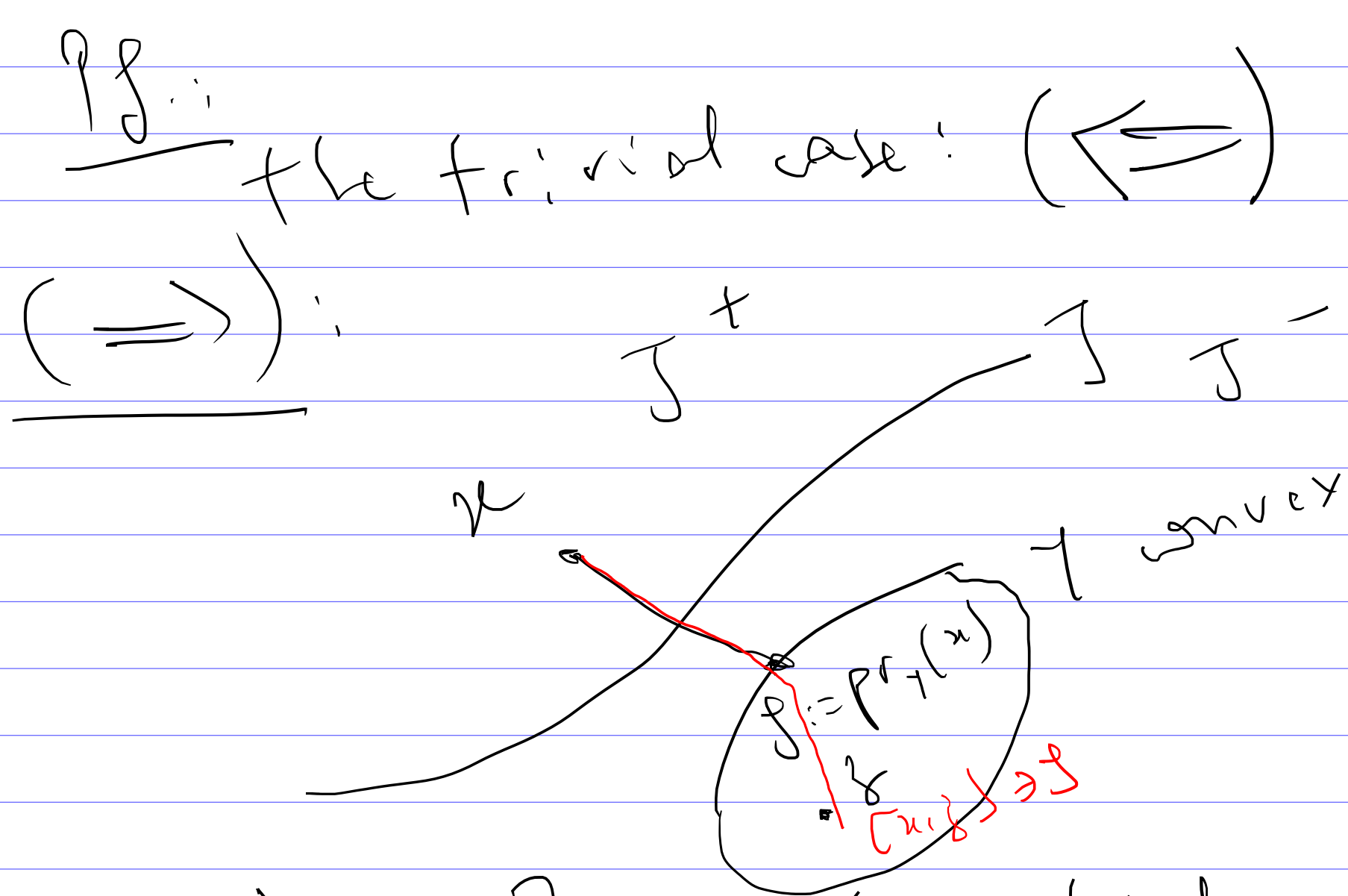
X median graph, $\gamma \subseteq X$ convex subgraph,

$x \in X$, $\gamma \in \mathcal{H}(X)$. Then:

γ separates x at $\text{pr}_\gamma(x)$

$(\Rightarrow)$

γ separates x and γ .



$\Rightarrow \exists [x, z]$ a geodesic that passes through y .

Since $x \in J^+$ and $y \in J^-$, J crosses J ,

Since J geodesic J crosses J exactly once,

$$J = \{z \in J \mid \forall z \in J\}$$

$$\Rightarrow J \subseteq J^- \Rightarrow J \text{ separates } x \text{ and } y. \quad \square$$

Property:

Let X be a median graph.

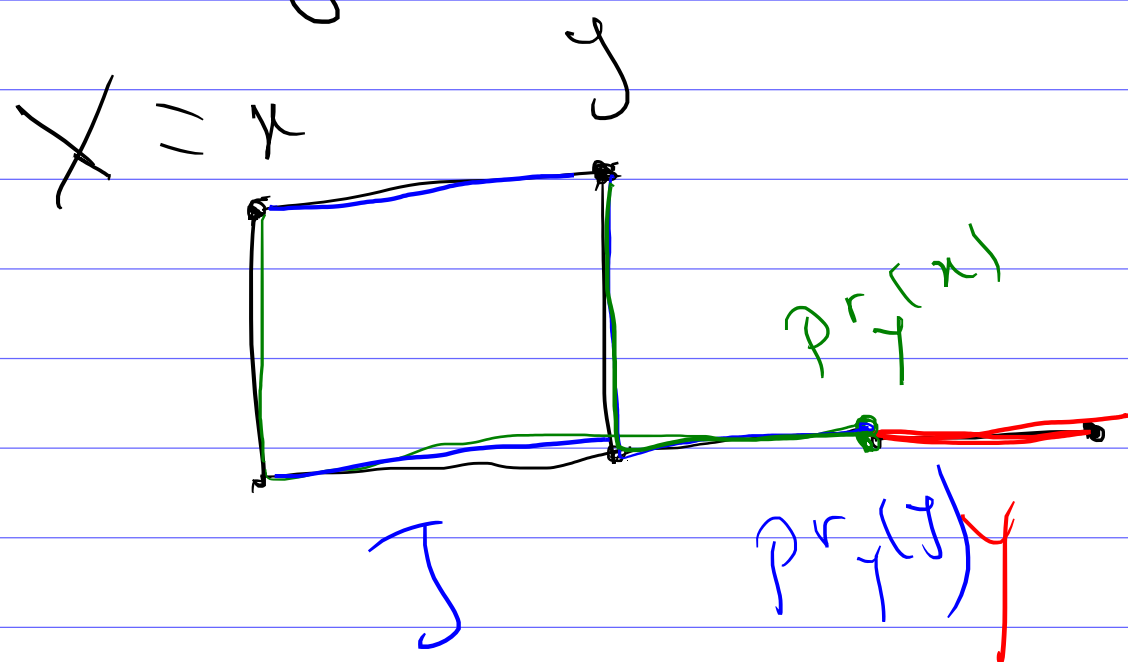
$Y \subseteq X$ convex subgraph

$x, y \in X$.

Then a hyperplane separates $pr_Y(x)$ and $pr_Y(y)$
iff it separates x and y and crosses Y .

Moreover, $d(pr_Y(x), pr_Y(y)) \leq d(x, y)$.

Counter ex.:



$x \in J^+, y \in J^-$,

but

$pr_Y(x), pr_Y(y) \in J$

Problem: J doesn't cross Y .